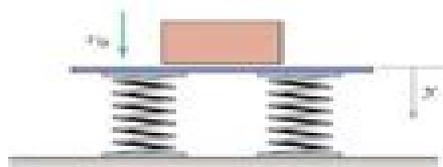


- 2/35** The body falling with speed  $v_0$  strikes and maintains contact with the platform supported by a nest of springs. The acceleration of the body after impact is  $a = g - cy$ , where  $c$  is a positive constant and  $y$  is measured from the original platform position. If the maximum compression of the springs is observed to be  $y_m$ , determine the constant  $c$ .

$$\text{Ans. } c = \frac{v_0^2 + 2gy_m}{y_m^2}$$



Problem 2/35

- 2/36** Particle 1 is subjected to an acceleration  $a = -kt$ , particle 2 is subjected to  $a = -kt$ , and particle 3 is subjected to  $a = -kt$ . All three particles start at the origin  $s = 0$  with an initial velocity  $v_0 = 10$  m/s at time  $t = 0$ , and the magnitude of  $k$  is 0.1 for all three particles (note that the units of  $k$  vary from case to case). Plot the position, velocity, and acceleration versus time for each particle over the range  $0 \leq t \leq 10$  s.

- 2/37** A self-propelled vehicle of mass  $m$  whose engine delivers constant power  $P$  has an acceleration  $a = P/(mv)$  where all frictional resistance is neglected. Determine expressions for the distance  $s$  traveled and the corresponding time  $t$  required by the vehicle to increase its speed from  $v_1$  to  $v_2$ .

$$\text{Ans. } s = \frac{m}{2P} (v_2^3 - v_1^3)$$

$$t = \frac{m}{2P} (v_2^2 - v_1^2)$$

- 2/38** A certain lake is proposed as a landing area for large jet aircraft. The touchdown speed of 100 mi/hr upon contact with the water is to be reduced to 20 mi/hr in a distance of 1500 ft. If the deceleration is proportional to the square of the velocity of the aircraft through the water,  $a = -Kv^2$ , find the value of the design parameter  $K$ , which would be a measure of the size and shape of the landing gear vanes that plow through the water. Also find the time  $t$  elapsed during the specified interval.

- 2/39** A particle moving along a straight line decelerates according to  $a = -kv$ , where  $k$  is a constant and  $v$  is velocity. If its initial velocity at time  $t = 0$  is  $v_0 = 4$  m/s and its velocity at time  $t = 2$  s is  $v = 1$  m/s, determine the time  $T$  and corresponding distance  $D$  for the particle speed to be reduced to one-tenth of its initial value.

$$\text{Ans. } T = 3.32 \text{ s, } D = 5.19 \text{ m}$$

- 2/40** The cone falling with a speed  $v_0$  strikes and penetrates the block of packing material. The acceleration of the cone after impact is  $a = g - cy^2$ , where  $c$  is a positive constant and  $y$  is the penetration distance. If the maximum penetration depth is observed to be  $y_m$ , determine the constant  $c$ .



Problem 2/40

- 2/41** The aerodynamic resistance to motion of a car is nearly proportional to the square of its velocity. Additional frictional resistance is constant, so that the acceleration of the car when coasting may be written  $a = -C_1 - C_2v^2$ , where  $C_1$  and  $C_2$  are constants which depend on the mechanical configuration of the car. If the car has an initial velocity  $v_0$  when the engine is disengaged, derive an expression for the distance  $D$  required for the car to coast to a stop.

$$\text{Ans. } D = \frac{1}{2C_2} \ln \left( 1 + \frac{C_2}{C_1} v_0^2 \right)$$



Problem 2/41

- 2/42** Compute the impact speed of a body released from rest at an altitude  $h = 500$  mi. (a) Assume a constant gravitational acceleration  $g_0 = 32.2$  ft/sec<sup>2</sup> and (b) account for the variation of  $g$  with altitude (refer to Art. 1.5). Neglect the effects of atmospheric drag.

# Dynamics Meriam Lecture Note

**D Sidentop**



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**Dynamics of the Rigid Solid with General Constraints by a Multibody Approach** Nicolae Pandrea, Nicolae-Doru Stanescu, 2016-05-03 Covers both holonomic and non holonomic constraints in a study of the mechanics of the constrained rigid body Covers all types of general constraints applicable to the solid rigid Performs calculations in matrix form Provides algorithms for the numerical calculations for each type of constraint Includes solved numerical examples Accompanied by a website hosting programs

**Nonlinear Oscillations, Dynamical Systems, and Bifurcations of Vector Fields** John Guckenheimer, Philip Holmes, 2013-11-21 From the reviews This book is concerned with the application of methods from dynamical systems and bifurcation theories to the study of nonlinear oscillations Chapter 1 provides a review of basic results in the theory of dynamical systems covering both ordinary differential equations and discrete mappings Chapter 2 presents 4 examples from nonlinear oscillations Chapter 3 contains a discussion of the methods of local bifurcation theory for flows and maps including center manifolds and normal forms Chapter 4 develops analytical methods of averaging and perturbation theory Close analysis of geometrically defined two dimensional maps with complicated invariant sets is discussed in chapter 5 Chapter 6 covers global homoclinic and heteroclinic bifurcations The final chapter shows how the global bifurcations reappear in degenerate local bifurcations and ends with several more models of physical problems which display these behaviors Book Review Engineering Societies Library New York 1 An attempt to make research tools concerning strange attractors developed in the last 20 years available to applied scientists and to make clear to research mathematicians the needs in applied works Emphasis on geometric and topological solutions of differential equations Applications mainly drawn from nonlinear oscillations American Mathematical Monthly 2

**Parallel Robots** Hamid D. Taghirad, 2013-02-20 Parallel structures are more effective than serial ones for industrial automation applications that require high precision and stiffness or a high load capacity relative to robot weight Although many industrial applications have adopted parallel structures for their design few textbooks introduce the analysis of such robots in terms of dynamics and control Filling this gap Parallel Robots Mechanics and Control presents a systematic approach to analyze the kinematics dynamics and control of parallel robots It brings together analysis and design tools for engineers and researchers who want to design and implement parallel structures in industry Covers Kinematics Dynamics and Control in One Volume The book begins with the representation of motion of robots and the kinematic analysis of parallel manipulators Moving beyond static positioning it then examines a systematic approach to performing Jacobian analysis A special feature of the book is its detailed coverage of the dynamics and control of parallel manipulators The text examines dynamic analysis using the Newton Euler method the principle of virtual work and the Lagrange formulations Finally the book elaborates on the control of parallel robots considering both motion and force control It introduces various model free and model based controllers and develops robust and adaptive control schemes It also addresses redundancy resolution schemes in detail Analysis and Design Tools to Help You Create

Parallel Robots In each chapter the author revisits the same case studies to show how the techniques may be applied The case studies include a planar cable driven parallel robot part of a promising new generation of parallel structures that will allow for larger workspaces The MATLAB code used for analysis and simulation is available online Combining the analysis of kinematics and dynamics with methods of designing controllers this text offers a holistic introduction for anyone interested in designing and implementing parallel robots *Fundamentals of Medical Ultrasonics* Michiel Postema,2011-02-23 Ultrasonic imaging is an economic reliable diagnostic technique Owing to recent therapeutic applications understanding the physical principles of medical ultrasonics is becoming increasingly important Covering the basics of elasticity linear acoustics wave propagation nonlinear acoustics transducer components ultrasonic imaging modes basi *Subject Catalog, 1975* Library of Congress,1975 *Applied Mechanics Reviews* ,1986 **Subject Catalog** Library of Congress, *Subject Guide to Books in Print* ,1996 **Scientific and Technical Books and Serials in Print** ,1984 *CoA Note* ,19?? **Scientific and Technical Books in Print** ,1972 **Books in Print Supplement** ,1985 *The Cumulative Book Index* ,1996 A world list of books in the English language *Library of Congress Catalog* Library of Congress,1971 Beginning with 1953 entries for Motion pictures and filmstrips Music and phonorecords form separate parts of the Library of Congress catalogue Entries for Maps and atlases were issued separately 1953 1955 **Books in Print** ,1982 **New Technical Books** New York Public Library,1975 **The Publishers' Trade List Annual** ,1966 *The Publishers Weekly* ,1972 **Samskrá um erlendan ritauka íslenzkra rannsóknarbókasafna** ,1978 **Library of Congress Catalogs** Library of Congress,1976

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