

Sensorless position estimation of Permanent-Magnet Synchronous Motors using a saturation model

Al Kasseem Jebai, François Malrait, Philippe Martin and Pierre Rouchon

Abstract—Sensorless control of Permanent-Magnet Synchronous Motors (PMSM) at low velocity remains a challenging task. A new well-established method consists in injecting a high-frequency signal and use the rotor saliency, both geometric and magnetic-saturation induced. This paper proposes a clear and original analysis based on second-order averaging of how to recover the position information from signal injection; this analysis blends well with a general model of magnetic saturation. It also proposes a simple parametric model of the saturated PMSM, based on an energy function which simply encompasses saturation and cross-saturation effects. Experimental results on a surface-mounted PMSM and an interior magnet PMSM illustrate the relevance of the approach.

Index Terms—Permanent-magnet synchronous motor, sensorless position estimation, signal injection, magnetic saturation, energy-based modeling, averaging.

I. INTRODUCTION

PERMANENT-Magnet Synchronous Motors (PMSM) are widely used in industry. In the so-called “sensorless” mode of operation, the rotor position and velocity are not measured and the control law must make do with only current measurements. While sensorless control at medium to high velocities is well understood, with many reported control schemes and industrial products, sensorless control at low velocity remains a challenging task. The reason is that observability degenerates at zero velocity, causing a serious problem in the necessary rotor position estimation.

A new well-established method to overcome this problem is to add some persistent excitation by injecting a high-frequency signal [1] and use the rotor saliency, whether geometric for Interior Permanent-Magnet machines or induced by main flux saturation for Surface Permanent-Magnet machines [2]–[10]. Signal injection is moreover considered as a standard building block in hybrid control schemes for complete drives operating from zero to full speed [11]–[15].

However to get a good position estimation under high-load condition it is important to take cross-saturation into account [16]–[26]. It is thus necessary to rely on a model of the saturated PMSM adapted to control purposes, i.e. rich enough to capture in particular cross-saturation but also simple enough to be used in real-time and to be easily identified in the field; see [27]–[32] for references more or less in this spirit.

The contribution of this paper, which builds on the preliminary work [33], is twofold: on the one hand it proposes a clear

and original analysis based on second-order averaging of how to recover the position information from signal injection; this analysis can accommodate to any form of injected signals, e.g. square signals as in [34], and blends well with a general model of magnetic saturation including cross-saturation. On the other hand a simple parametric model of the saturated PMSM, well-adapted to control purposes, is introduced; it is based on an energy function which simply encompasses saturation and cross-saturation effects.

The paper runs as follows: section II presents the saturation model. In section III position estimation by signal injection is studied thanks to second-order averaging. Section IV is devoted to the estimation of the parameters entering the saturation model using once again signal injection and averaging. Finally section IV-C experimentally demonstrates on two kinds of motors (with interior magnets and surface-mounted magnets) the relevance of the approach and the necessity of considering saturation to correctly estimate the position.

II. AN ENERGY-BASED MODEL OF THE SATURATED PMSM

A. Notations

In the sequel we denote by $x_{ij} := (x_i, x_j)^T$ the vector made from the real numbers x_i and x_j , where ij can be dq , $\alpha\beta$ or $\gamma\delta$. We also define the matrices

$$M_\mu := \begin{pmatrix} \cos \mu & -\sin \mu \\ \sin \mu & \cos \mu \end{pmatrix} \quad \text{and} \quad K := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix},$$

and we have the useful relation

$$\frac{dM_\mu}{d\mu} = KM_\mu = M_\mu K.$$

B. Energy-based model

The model of a two-axis PMSM expressed in the synchronous $d-q$ frame reads

$$\frac{d\phi_{dq}}{dt} = u_{dq} - R i_{dq} - \omega K(\phi_{dq} + \phi_m) \quad (1)$$

$$\frac{J}{n^2} \frac{d\omega}{dt} = \frac{3}{2} i_{dq}^T K(\phi_{dq} + \phi_m) - \frac{\tau_L}{n} \quad (2)$$

$$\frac{d\theta}{dt} = \omega, \quad (3)$$

with ϕ_{dq} flux linkage due to the current; $\phi_m := (\lambda, 0)^T$ constant flux linkage due to the permanent magnet; u_{dq} impressed voltage and i_{dq} stator current; ω and θ rotor (electrical) speed and position; R stator resistance; n number of pole pairs; J inertia moment and τ_L load torque. The physically impressed voltages are $u_{\alpha\beta} := M_\mu u_{dq}$ while the physically measurable

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Sensorless Position Estimation Of Permanent Magnet:

Sensorless Position Estimation in Sinusoidal Permanent Magnet Synchronous Motor Deepak Shivaram Shet,1998 **Real Time Implementation of Sensorless Position Estimation in a Permanent Magnet Synchronous Motor Using DSP TMS320C24X** Rohit Khetarpal,2003 **Position Sensorless Control Techniques for Permanent Magnet Synchronous Machine Drives** Gaolin Wang,Guoqiang Zhang,Dianguo Xu,2019-11-15 The book focuses on position sensorless control for PMSM drives addressing both basic principles and experimental evaluation It provides an in depth study on a number of major topics such as model based sensorless control saliency based sensorless control position estimation error ripple elimination and acoustic noise reduction Offering a comprehensive and systematic overview of position sensorless control and practical issues it is particularly suitable for readers interested in the sensorless control techniques for PMSM drives The book is also a valuable resource for researchers engineers and graduate students in fields of ac motor drives and sensorless control **The Electric Generators Handbook - 2 Volume Set** Ion Boldea,2005-11-16 The modern world hungers for electricity Traditionally this hunger was sated with predominantly constant speed regulated synchronous generators However new demands require the stable quick and efficient delivery and control offered by variable speed generators Surveying all of the technologies used to satisfy the world s demand for o *Control of Electric Machine Drive Systems* Seung-Ki Sul,2011-04-20 A unique approach to sensorless control and regulator design of electric drives Based on the author s vast industry experience and collaborative works with other industries Control of Electric Machine Drive Systems is packed with tested implemented and verified ideas that engineers can apply to everyday problems in the field Originally published in Korean as a textbook this highly practical updated version features the latest information on the control of electric machines and apparatus as well as a new chapter on sensorless control of AC machines a topic not covered in any other publication The book begins by explaining the features of the electric drive system and trends of development in related technologies as well as the basic structure and operation principles of the electric machine It also addresses steady state characteristics and control of the machines and the transformation of physical variables of AC machines using reference frame theory in order to provide a proper foundation for the material The heart of the book reviews several control algorithms of electric machines and power converters explaining active damping and how to regulate current speed and position in a feedback manner Seung Ki Sul introduces tricks to enhance the control performance of the electric machines and the algorithm to detect the phase angle of an AC source and to control DC link voltages of power converters Topics also covered are Vector control Control algorithms for position speed sensorless drive of AC machines Methods for identifying the parameters of electric machines and power converters The matrix algebra to model a three phase AC machine in d q n axes Every chapter features exercise problems drawn from actual industry experience The book also includes more than 300 figures and offers access to an FTP site which provides MATLAB programs for selected problems The book s practicality and

realworld reliability make it an invaluable resource for professionals and engineers involved in the research and development of electric machine drive business industrial drive designers and senior undergraduate and graduate students To obtain instructor materials please send an email to pressbooks@ieee.org To visit this book's FTP site to download MATLAB codes please click on this link ftp.ftp.wiley.com/public/sci_tech_med/electric_machine MATLAB codes are also downloadable from Wiley Booksupport Site at <http://booksupport.wiley.com>

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Electronics Society IEEE Industrial Electronics Society. Conference,2003 Observer Techniques for Rotor Speed and Position Estimation for Permanent Magnet Assisted Synchronous Reluctance Machines Antonio Barrio Barrio,2018 The purpose of the project is to achieve a robust SENSORLESS control of a Permanent Magnet assisted Synchronous Reluctance Motor It is a part of an industrial project call CICYT carried out at MCIA research group in UPC This thesis concentrates on a special electrical control method called Field Oriented Control FOC Computer simulations of machine fed with a two levels voltage source inverter were performed Analisis of the robustnes of most usual sensorless methods have been performed and results corroborate that general sensorless observers methods are more insensitive to the gaussian noise **Second International Conference on Power Electronics, Machines, and Drives (PEMD 2004)** ,2004 *Proceedings of ... International Conference on Power Electronics and Drive Systems* ,2005 **ICEMS'2001** Fengxiang Wang,Renyuan Tang,2001

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